# **Bit-Precise LTL Model Checking**

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#### Abstract

Complete verification of unmodified code is a challenging task, well-motivated by the costs of software debugging. In this work we rise to the challenge by proposing a model checking method that operates on unmodified parallel programs, specifically accepting LLVM bitcode as input. Apart from being complete, our method proves correctness of a program w.r.t. a temporal specification and is sound w.r.t. arithmetic overflows of integer variables. To overcome the limitations of classical model checking: state space explosion, state matching, etc. we further propound to reduce the model checking problem to a specific instance of the non-termination checking and lift the recently proposed *property directed reachability* to compute approximations of *recurrent sets*.

### 2 Avoid Loop Unrolling: Idea

Apart from expensive state comparison the present approach is also limited by the fact that program loops may be exhaustively unrolled during verification. A recently proposed property guided reachability (PDR) [2] avoids unrolling loops while also allowing extensions for LTL and CTL model checking by proving unreachability among fair states. We propose an alternative extension via non-termination analysis [3], specifically to lift PDR to compute approximations of recurrent sets of evaluations pertaining to fair states.

### Formalisation

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**Definition**: By Reach(l) we denote the set of evaluations at location l reachable from the initial location, i.e.  $\forall \mathbf{x} \in Reach(l), (l_0, \mathbf{x}_0) \rightsquigarrow (l, \mathbf{x})$ .

# **1 Present State**

Our tool accepts LLVM bitcode as the program and an LTL formula as the specification where the atomic propositions are quantifier free *bit-vector* formulae over global variables. Since variable evaluations are also represented as bit-vector formulae, comparing two states while searching for a fair cycle within the system can be reduced to *satisfiability modulo theories* query. The major limitation of the present state arises from this query being quantified, thus increasing the complexity of individual state comparisons.

#### 1.1 Work Flow

The figure below illustrate how control explicit—data symbolic model checking transforms the input pair (program  $\mathcal{P}$ , specification  $\mathcal{A}$ ) to generate the set-reduced transition system  $\mathfrak{P}_S$ . The formulae representing variable evaluations are cumulatively collected along the paths in both the program and the specification automaton.



**Definition**: By Recur(l) we denote a set of evaluations, such that  $\forall \mathbf{x} \in Recur(l)$  there is a path from l to l that performs an identity on  $\mathbf{x}$ , i.e.  $(l, \mathbf{x}) \rightsquigarrow (l, \mathbf{x})$ . **Definition**: Let X be a set of evaluations characterised by  $\Phi$ , i.e.  $\forall \mathbf{x}, \Phi(\mathbf{x}) \Leftrightarrow \mathbf{x} \in X$ . Then by  $\uparrow X$  we denote any *over-approximation* of X, i.e.  $\forall \mathbf{x}, \Phi(\mathbf{x}) \Rightarrow \mathbf{x} \in \uparrow X$ . And by  $\downarrow X$  we denote any *under-approximation* of X, i.e.  $\forall \mathbf{x}, \Phi(\mathbf{x}) \Leftarrow \mathbf{x} \in \downarrow X$ .

**Theorem**: For a program  $\mathcal{P}$  and a specification  $\varphi$  let F be the set of fair locations. Then

 $\exists l_F \in F, \downarrow Reach(l_F) \cap \downarrow Recur(l_F) \neq \emptyset \Rightarrow \mathcal{P} \not\models \varphi$ 

 $\forall l_F \in F, \uparrow Reach(l_F) \cap \uparrow Recur(l_F) = \emptyset \Rightarrow \mathcal{P} \models \varphi.$ 

The above theorem leads to a model checking algorithms that iteratively refines the approximations of Reach(l) and Recur(l) for a fair location l until one of the termination conditions becomes valid.

### **3 Avoid Loop Unrolling: Implementation**

As the driving force behind such iterative refinement we propose using PDR, lifted according to the following points:

- refine Recur(l) sets using counter-examples to recurrence (CTR) and Reach(l) sets using counter-examples to induction;
- localise the refinements to program locations;

The set-based reduction using bit-vector formulae is not the only output of our tool SYMDIVINE [1]. We can also generate the state space encoded with BDDs or generate the control flow graph (supporting other tools with access to parallel programs).

### **1.2 Experiments**

We have evaluated SYMDI-VINE on examples translated from C programs. Apart from Erik Koskinen's tool (reducing model checking to termination analysis) we also com-

Name	Property	Koskinen	NUXMV	SymDi
acqrel	$\mathcal{G}(a \Rightarrow \mathcal{F} b)$	14.18	0.31	28.25
apache	$\mathcal{G}(a \Rightarrow \mathcal{G} \mathcal{F} b)$	197.4	>60	47.50
fig8-2007	$\mathcal{G}(a \Rightarrow \mathcal{G} \mathcal{F} b)$	27.94	0.25	>60
pgarch	$\mathcal{GF}a$	15.20	>60	0.83
win1	$\mathcal{G}(a \Rightarrow \mathcal{F} a)$	539.0	7.15	0.62
win3	$\mathcal{F}\mathcal{G}a$	15.75	0.04	0.18
1	$\mathcal{F}\mathcal{G}a$	11.0	2.43	0.7
12	$\mathcal{F}(a \land \neg \mathcal{G} a)$	3.9	0.41	0.23

• extend the method to the bit-vector theory (similarly as in [4]).

**Under-approximation** Search for under-approximations (w.r.t. a fair location  $l_F$ ) has two cooperating stages:

standard PDR with P ≡ ¬at\_l<sub>F</sub> describing the safe states ⇒ x ∈ Reach(l<sub>F</sub>)
 PDR with P ≡ ¬(at\_l<sub>F</sub> ∧ x), initial state set to (l<sub>F</sub>, x), and limited to the strongly connected component containing l<sub>F</sub>.

**Over-approximation** The standard definition of the recurrent set requires quantifier alternation: Let X, X' be the sets of program variables for the current and the next state and I the input variables. Then G is a recurrent set w.r.t. to the cycle relation R iff

 $\forall X \exists X' \exists I, \ G[X] \Rightarrow R[X, X', I] \land G'[X'].$ 

It follows that a CTR is any evaluation without either a predecessor or a successor. The figure below illustrates the search for single-step CTRs.



pare with NOAMV (using Sivi I-
based bounded model check-
ing): two state-of-the-art model
checkers.

## References

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  F. Somenzi, Z. Hassan, Z. Yan, In *Proc. of FMCAD*, 2011
- [3] Proving Non-termination A. Gupta, T. Henzinger, R. Majumdar, A. Rybalchenko, R. Xu, In Proc. of POPL, 2008
- [4] **QF\_BV Model Checking with Property Directed Reachability** T. Welp, A. Kuehlmann, In *Proc. of DATE*, 2013

**Description** The task is to refine  $F^l$  based on the new  $F^{l'}$ , assuming the invariant  $\forall i < k, \forall X \exists X' \exists I, \ F_i^l \Rightarrow \rho \land F_i^{l'}$ 

 $\begin{array}{ll} \bullet \quad \text{initialise} & F_k^l \coloneqq F_{k-1}^l \\ \bullet \quad \text{find potential CTR} & \mathcal{M} \coloneqq \operatorname{sat}(F_k^l \wedge \rho \wedge (F_{k-1}^{l'} \wedge \neg F_k^{l'})) & c, c' \coloneqq \mathcal{M}_{|X}, \mathcal{M}_{|X'} \\ \bullet \quad \text{check } c & q \coloneqq \operatorname{sat}(c \wedge \rho \wedge F_k^{l'}) \\ - & q = sat \begin{array}{ll} \left\{ \begin{array}{c} \rho[X, X', I] & \hat{c} \wedge F_{k-1}^l \wedge \rho \wedge c' \dots sat \\ \rho[X, X'] & \hat{c} \wedge F_{k-1}^l \wedge \rho \wedge F_k^{l'} \dots sat \end{array} \right. & \hat{c} \Rightarrow \neg c \\ - & q = unsat & \check{c} \wedge \rho \wedge F_k^{l'} \dots unsat & c \Rightarrow \check{c} \end{array}$